

GREGORIO MARCHESINI

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Education

KTH Royal Institute of Technology

March 2023 - present

Doctoral student, Intelligent and Autonomous systems, Division of Decision and Control Systems

Stockholm, Sweden

TuDelft Delft University of Technology

August 2021 - January 2022

Exchange program : Master of Science in Aerospace Engineering, Space exploration track

Delft, Netherlands

KTH Royal Institute of Technology

August 2020 - December 2022

Master of Science in Aerospace Engineering, Space Engineering track

Stockholm, Sweden

University of Bologna

September 2017 - July 2020

Bachelor of Science in Aerospace Engineering

Forli, Italy

Research and Work experience

C.I.R.I Aerospace

February 2020 - June 2020

Internship

Forli, Italy

- The research project focused on the evaluation of the Wavelet Decomposition method as possible tool for recovering temporal *doppler* shift information for Deep Space communication operations

KTH Royal Institute of Technology

February 2022 - present

Research Assistant at The Space and plasma physics department

Stockholm, Sweden

- Analysis of the Lyman Alpha radiation features from the Jovian moon Ganymede. The analysis aimed at detecting possible radiation anomalies related to water plumes escaping from Ganymede. I worked under the supervision of professor Lorenz Roth.

MIST-MIniatuRe Student saTellite

January 2021 - May 2021

Attitude Determination and Control System team member

Stockholm, Sweden

- As AOCS engineer in the project, I analysed compared and implemented different calibration algorithms as possible solutions for the MIST's on-board magnetometer calibration

Rocket Factory Augsburg

October 2022 - December 2022

Attitude Determination and Control System team member

Augsburg, Germany

- I developed different orbit propagation and attitude control routines for the maiden flight of the RFA1 launcher which will occur in 2024.

SymAware project

March 2023 - Present

Researcher

Stockholm, Sweden

- The SymAware project is an EU-funded project with the goal of developing different notions of situational awareness for multi-agent systems involving autonomous systems as well as human interacting in the same environment. I contribute to the project by developing theoretical and algorithmic solutions for multi-agent systems planning and control under spatio-temporal and communications constraints.

Projects

Master's Thesis project in Aerospace Engineering

February 2022 - October 2022

Inspection of orbital structures

Stockholm, Sweden

- The project involves the development of an MPC controller with guaranteed safety through Control Barrier Functions constraints for a prototype inspection mission of the outer structure of the International Space Station by means of a fleet of CubeSats. The result of the thesis was published at the Conference on Decision and Control 2023

Space Debris Removal preliminary mission design

September 2021 - October 2021

Team : G. Marchesini, K. Lamboley, M. Svalstedt, M. Tjernström, W. Lannhard

Stockholm, Sweden

- Research on state-of-the-art solutions for space debris removal
- Design of launch system simulator
- Development of orbital mechanics and cost analysis for the mission

Technical Skills

Programming: Python, MATLAB, C++, Latex, Excel, Arduino

Software and collaboration platforms: SolidEdge, XLFR5, GitHub, GHOST

Languages: Italian, English

Publications

Marchesini G, Liu S, Lindemann L, Dimarogonas DV. Sampling-based planning under spatio-temporal constraints: A Forward Invariance approach. Under preparation.

Marchesini G, Liu S, Lindemann L, Dimarogonas DV. A Communication Consistent Approach to Signal Temporal Logic Task Decomposition in Multi-Agent Systems. Under revision for Transactions on Automatic Control

G. Marchesini, S. Liu, L. Lindemann and D. V. Dimarogonas, "Decentralized Control of Multi-Agent Systems Under Acyclic Spatio-Temporal Task Dependencies," 2024 IEEE 63rd Conference on Decision and Control (CDC), Milan, Italy, 2024, pp. 5211-5217,

G. Marchesini, S. Liu, L. Lindemann and D. V. Dimarogonas, "Communication-Constrained STL Task Decomposition Through Convex Optimization," 2024 American Control Conference (ACC), Toronto, ON, Canada, 2024, pp. 3517-3523.

Roth, L., Marchesini, G., Becker, T.M., Hoeijmakers, H.J., Molyneux, P.M., Retherford, K.D., Saur, J., Mogan, S.R.C. and Szalay, J.R., 2023. Probing Ganymede's atmosphere with HST Ly α images in transit of Jupiter. The Planetary Science Journal, 4(1), p.12.

G. Marchesini, P. Roque and D. V. Dimarogonas, "Corridor MPC for Multi-Agent Inspection of Orbiting Structures," 2023 62nd IEEE Conference on Decision and Control (CDC), Singapore, Singapore, 2023, pp. 5765-5771,